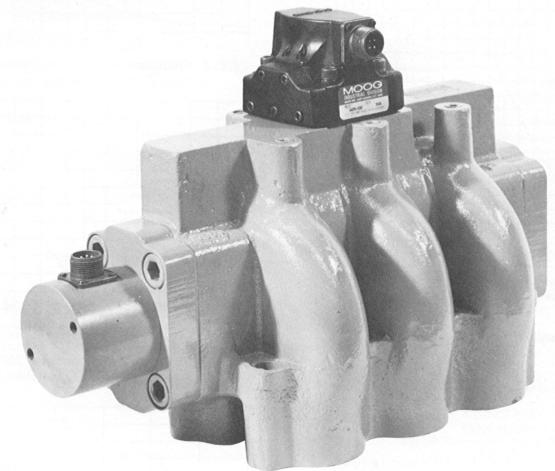


Model 79-500 **High Flow Servovalve**



Features

- symmetrical, four-way, closed-center flow control
- · modular pilot valve
- separate pilot supply and return ports
- · rugged, cast iron, power valve body
- long life, hardened spool and bushing
- electrical feedback allows convenient change in rated flow to help optimize system performance
- spool position LVDT electrically isolated from hydraulic fluid
- optional DCDT
- small amplitude dynamic response to 80 Hz

These three-stage servovalves provide high dynamic response for precision control of position, velocity, or force in systems requiring from 150 hp to 1000 hp. Maximum rated flow for these servovalves is 750 gpm at 1000 psi drop. Operating supply pressure can be as high as 4000 psi.

Electrical feedback of power valve spool position is provided by an LVDT. A separate exciter, demodulator and servoamplifier are necessary to close the spool position servoloop.

Alternatively, an optional dc to dc transducer can be supplied. This DCDT has a self-contained exciter and demodulator which simplifies the external electronics.

Performance

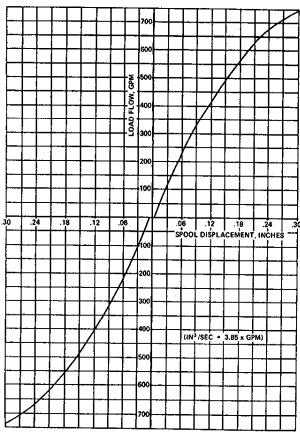


Fig. 1 Power Valve Flow Gain @ 1000 psi Valve Drop

Pilot Valve Specifications

•	
Model Number	AO76-232
Rated Flow at 1000 psi	5.0 gpm
Rated Input series coils parallel coils	
Coil Resistance at +25° C	80Ω each (± 10%)
Approximate Coil Inductance series coils parallel coils	
Power Valve Specifications	
Spool end area	1.57 in ²
Spool flow gain at 1000 psi (in low flow region)1	1.6 X 10 ⁴ <u>in³/sec</u> inch
Spool stroke for 425 gpm rated flow	± 0.125 in.

for 720 gpm rated flow ... \pm 0.275 in.

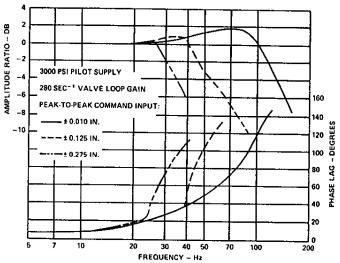


Fig. 2 Frequency Response with 280 sec⁻¹ Loop Gain and 3000 psi Pilot Supply

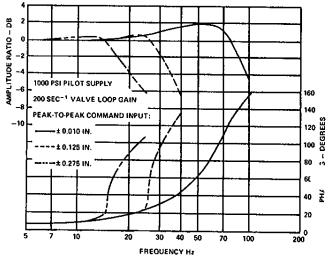


Fig. 3 Frequency Response with 200 sec⁻¹ Loop Gain and 1000 psi Pilot Supply

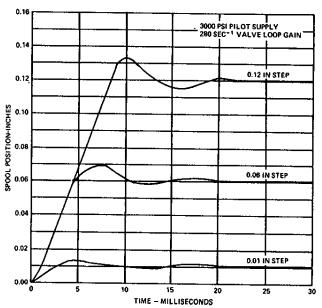
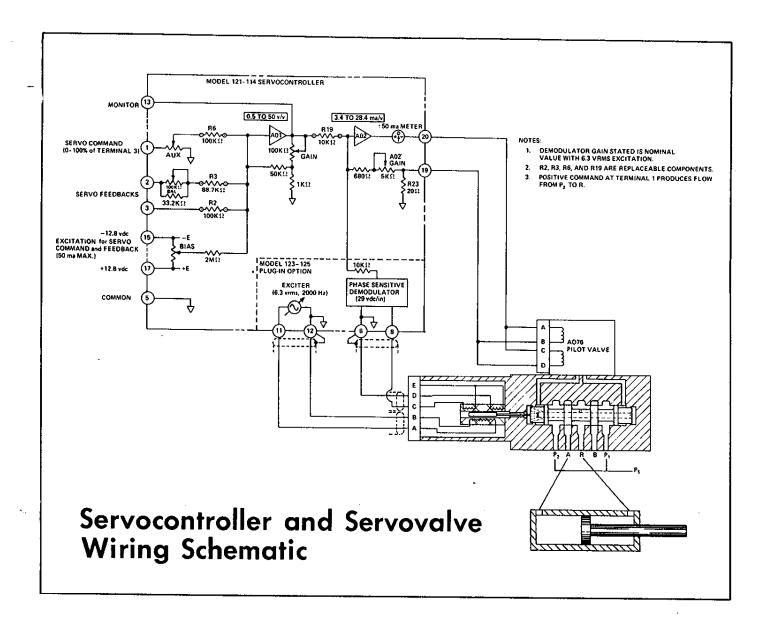


Fig. 4 Small Amplitude Step Response



Гуре	LVDT*	INC.
Excitation Frequency minimum maximum recommended	400 Hz 5000 Hz 2000 to 4000 Hz	HON TOUR OF SENSITIVITY OF SENSITIVITY
Maximum Excitation Voltage	15 vrms	*
Approximate Excitation Power (at 2000 Hz)	6.5 x 10 ⁻⁴ va/volt	0.6 PHASE
Recommended Load Impedance	≥50 KΩ	NOTE: INDIVIDUAL UNITS MAY VARY 10%
Output Sensitivity and Phase Shift	See Figure 5	0.4 0.5 0.7 1.0 1.5 2 3 4 5 5 EXCITATION FREQUENCY – KILOHERTZ

Set-up and Operation

SERVOAMPLIFIER

The Model 121-114 is a convenient servoamplifier for use with the 79-500 servovalve. An optional plug-in circuit card, the Model 123-125, contains an exciter and demodulator for operation of the spool position LVDT.

The ac excitation is nominally 6.3 vrms (adjustable) and the carrier frequency is 2000 Hz. The 2000 Hz frequency is recommended to achieve best servovalve response; however, a lower frequency may be necessary if a long cable run is required.

With the nominal excitation of 6.3 vrms at 2000 Hz, the spool position LVDT will have a sensitivity (from Figure 5) of $1.07 \times 6.3 = 6.74$ vrms/inch. The demodulator gain of the Model 123-125 circuit card is 4.3 vdc/vrms.

SERVOVALVE LOOP GAIN

The inner loop gain of the 79-500 servovalve when operating with 3000 psi pilot supply pressure and with the coils of the pilot valve in parallel is determined by:

$$K_{IL} = \frac{K_A K_{PV} K_D K_X}{A_S}$$

where

 K_{1L} = servovalve inner loop gain sec⁻¹

K_A = servoamplifier gain ma/vdc

KpV = pilot valve gain

 $= \frac{5.0 \text{ gpm x } 3.85 \frac{\text{in}^3/\text{sec}}{\text{gpm}} \sqrt{\frac{3000 \text{ psi}}{1000 \text{ psi}}}}{40 \text{ ma}}$

 $= 0.83 \frac{in^3/sec}{ma}$

K_D = demodulator gain = 4.3 vdc/vrms

 K_X = LVDT gain = 6.74 vrms/inch

As = power spool end area = 1.57 in²

For the recommended maximum inner loop gain of 280 sec⁻¹:

$$K_A = \frac{280 \times 1.57}{0.83 \times 4.3 \times 6.74} = 18.3 \text{ ma/vdc}$$

LOOP GAIN SET-UP

- Connect amplifier terminals 19 and 20 to the pilot valve electrical connector per the schematic on Page 3.
- Monitor terminal 13 (output of A01) and adjust the BIAS pot on the front panel to obtain first +1.0 vdc, then -1.0 vdc.
- Monitor the valve current by reading the front panel meter (±50 ma full scale) or by measuring the voltage drop across the 20Ω sensing resistor R23 (terminal 19 to terminal 5). The latter is the more accurate method.
- Adjust the A02 GAIN pot located on the back of the servocontroller board to obtain the desired amplifier gain with the -1.0v bias input. Note that the 18.3 ma/vdc is a calculated maximum value. It is recommended that the amplifier gain be turned down the first time supply pressure is applied. It may not be possible to operate with satisfactory valve stability at the maximum loop gain as both the pilot valve and LVDT have about ±10% gain tolerances.

OUTER SERVOLOOP GAIN

The gain of the 79-500 servovalve in the outer loop will be:

$$K_{VAL} = \frac{K_S}{K_D K_X}$$

where

 K_{VAL} = overall valve gain $\frac{in^3/sec}{vdc}$

K_S = power valve flow gain (see Specifications, Page 2)

K_D = demodulator gain vdc/vrms

K_X = LVDT gain vrms/inch

 $K_{VAL} = \frac{1.6 \times 10^4}{4.3 \times 6.74} = 550. \frac{\text{in}^3/\text{sec}}{\text{vdc}}$

Note that the power valve flow gain is specified for operation at 1000 psi supply. This gain must be corrected for operation at other supply pressures by multiplying the square root of the ratio of supply pressures.

The input amplifier, A01, of the Model 121-114 can be used for summing servo command and feedback signals. The A01 GAIN control (accessible on the front panel) provides a convenient outer loop gain adjustment.

Specifications

Maximum rated flow at 1000 psi valve drop
Internal leakage at 1000 psi supply
Recommended supply pressures pilot valve
third-stage power valve
Operating temperature
Fluids
Seals
Recommended supply filtration
Weight 120 pounds

Performance Summary

(with 3000 psi Pilot Pressure and Valve Loop Gain of 280 sec⁻¹)

	servoloop scaled for full power valve output at:	
	± 0.125 inch spool stroke	± 0.275 inch spool stroke
Flow at 1000 psi supply	425 gpm	720 gpm
Linearity	See Figure 1 <±5% ±0.003 inch	
Flow symmetry		
Spool Overlap		
Typical blocked load pressure gain at null 10	% to 30% P _s /.00	1 inch spool travel
Hysteresis	< 0	.6%
Threshold	< 0.3%	
Null Shift with 500 psi change in pilot supply pressure with 500 psi change in pilot return pressure with 50° change in fluid temperature	< ±1.5% < ±1.5% < ±1.5%	< ±0.7% < ±0.7% < ±0.7%
Dynamic response at \pm 100% input amplitude $<\pm 2$ db amplitude ratio	to 48 Hz 46 Hz	to 28 Hz 34 Hz

Installation Details

